

## **Differential pressure controller (PN 16)**

**AVPL** – return mounting, adjustable setting

#### Description



AVPL is a self-acting differential pressure controller primarily for use in district heating systems. The controller closes on rising differential pressure.

The controller has a control valve and an actuator with one control diaphragm.

It can be used on primary side of house substations for smaller systems such as one and two-family houses.

The controller could be used to control the differential pressure across radiator systems and similar systems to keep a constant differential pressure even with a variable system resistance  $k_{va}$  and/or supply pressure  $\Delta p_0$ .

#### Main data:

- DN 15
- k<sub>vs</sub> 1.0, 1.6 m<sup>3</sup>/h
- PN 16
- Setting range: 0.05-0.25 bar (factory setting 0.1 bar)
- Temperature:
  - Circulation water / glycolic water up to 30%:
    2 ... 120 °C
- Connections:
- Ext thread (weld-on and thread tailpieces)

## Ordering

# Example: Differential pressure controller, return mounting, DN 15, $k_{vs}$ 1.0, PN 16, setting range 0.05 - 0.25 bar, $t_{max}$ 120 °C, ext. thread

- 1× AVPL DN 15 controller Code No: **003L5030** 

#### Option:

- 1× Weld-on tailpieces Code No: **003H6908** 

### **AVPL** Controller

Picture	<b>DN</b> (mm)	k <sub>vs</sub> (m³h)	Connection	<b>Δp setting range</b> (bar)	Code No. *	
	15	1.0	Ext. thread acc. to ISO 228/1	G ¾ A	0.05-0.25	003L5030
		1.6	Ext. tillead acc. to 130 226/1			003L5031

<sup>\*</sup> Controller incl. impulse tube set AH (1.5 m at k<sub>vs</sub> 1.0 and 2.5 m at k<sub>vs</sub> 1.6) and nipple Gl/16 - R<sup>3</sup>/6 for impulse tube connection to pipe

## Accessories

Picture	Type designation	DN	DN Connection		Code No.	
	Weld-on tailpieces	-			003H6908	
	External thread tailpieces	15	Conical ext. thread acc. to EN 10226-1	R 1/2	003H6902	
		Description: - 1× copper tube Ø 3 × 1 mm - 2× fitting for imp. tube connection to actuator and pipe G 1/16		1.5 m	003L3561	
	Impulse tube set AH			2.5 m	003L5043	
				5 m	003L3562	
	Impulse tube set AH for pressure reduction	Description: - 1× stainless steel tube Ø 0.8 × 0.2 mm - 2× fitting for imp. tube connection to actuator and pipe G 1/16		0.8 m	003L3560	
<u>—</u>	Fitting for impulse tube co	G <sup>1</sup> / <sub>16</sub> - R <sup>3</sup> / <sub>8</sub>	003L5042			
	Tritting for impulse tube co	G 1/16 - R 1/4	003L8151			
	EPP insulation box <sup>1)</sup>					
	10 EPDM o-rings for impulse tube					

<sup>1)</sup> The material for the insulation box is approved according to the fire hazard classification B2, DIN 4102.

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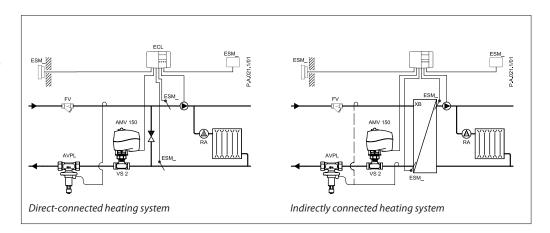
## Differential pressure controller AVPL (PN 16)

## **Technical data**

Nominal diameter	DN	15				
k <sub>vs</sub> value	m³/h	1.0	1.6			
Cavitation factor z		0.5				
Nominal pressure	PN	16				
Max. differential pressure	bar	4.5				
Medium		Circulation water / glycolic water up to 30%				
Medium pH		Min. 7, max. 10				
Medium temperature	°C	2	120			
Connections	valve	External thread				
Connections	tailpieces	Weld-on and external thread				
Materials						
Valve body, spindle, etc.		Dezincing free brass CuZn36Pb2As				
Cone, seat and spring		Stainless steel				
Diaphragm and O-ring		EPDM				
Institute a trub a		Copper tube Ø 3 × 1 mm				
Impulse tube		Stainless steel tube Ø $0.8 \times 0.2 \times 800$ mm				

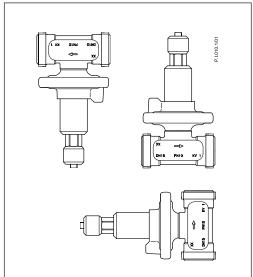
## **Application principles**

The controller AVPL could be installed in the return pipeline only.



## Installation positions

The controllers can be installed in any position.



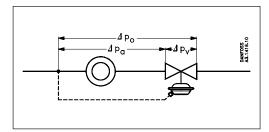
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#### Sizing



Considering the correlation between the capacity of the system  $k_{va}$ , the system flow Q and the differential pressure  $\Delta p_a$ , the controller setting  $\Delta p_i$  is determined by:

$$\Delta p_i = \Delta p_a = (Q/k_{va})^2$$

Based on the stated differential pressure of the district heating  $\Delta p_o$  and the calculated differential pressure of the system  $\Delta p_{a'}$  the differential pressure across the controller valve is expressed as:

$$\Delta p_v = \Delta p_o - \Delta p_a$$

Finally, a check is required to ensure that the actual capacity of the controller  $k_{\nu\nu}$  is smaller than its max. capacity  $k_{\nu s}$ 

$$k_{vv} = Q / \sqrt{\Delta p_v} \le k_{vs}$$

#### **Example:**

A heating system with a number of parallel hot surfaces.

Required flow:

 $Q = 0.24 \text{ m}^3/\text{h}$ 

Total capacity of the system determined to be  $k_{va} = 0.6 \text{ m}^3/\text{h}$ .

Calculation of the differential pressure across the system:

$$\Delta p_a = (Q/k_{va})^2 = (0.24/0.6)^2 = 0.16 \text{ bar (16 kPa)}$$

The differential pressure from the district heating is stated to be:

$$\Delta p_o = 0.5 \text{ bar } (50 \text{ kPa}) \text{ min}$$

Calculation of the differential pressure across the controller valve:

$$\Delta p_v = \Delta p_o - \Delta p_a = 0.5 \text{ bar} - 0.16 \text{ bar} = 0.34 \text{ bar} (34 \text{ kPa})$$

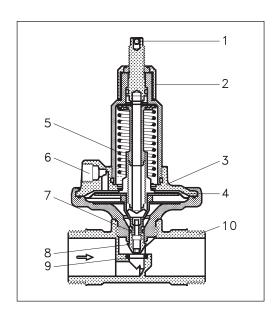
In this example the capacity of the controller valve is:

$$k_{vv} = Q/\sqrt{\Delta p_v} = 0.24/\sqrt{0.34} = 0.412 \text{ m}^3/\text{h}$$

which is less that the max. capacity of the controller =  $k_{vs} = 1.0 \text{ m}^3/\text{h}$ .

## Design

- **1.** Spindle for differential pressure setting
- 2. Bushing
- **3.** Actuator
- 4. Control diaphragm
- **5.** Setting spring for diff. pressure control
- 6. Connection for impulse tube
- **7.** O-ring
- 8. Pressure relieved valve cone
- 9. Seat
- 10. Valve body



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#### Differential pressure controller AVPL (PN 16)

#### **Function**

AVPL is a proportional controller which operates according to the following principle: The degree of opening of the control valve /  $k_v$ value is proportional to the deviation between the controlled and set differential pressure,  $\Delta p_a - \Delta p_s$ . Thus the resistance/k<sub>v</sub> value is adjusted to the actual differential pressure  $\Delta p_v$ and accordingly, the flow Q is adjusted so that the desired differential pressure  $\Delta p_{\text{a}}$  is obtained across the actual resistance  $k_{va}$  in the system.

Differential pressure across the system

$$\Delta p_a = \left(\frac{Q}{k_{va}}\right)^2$$

Differential pressure across the controller

$$\Delta p_{v} = \left(\frac{Q}{k_{vv}}\right)^{2}$$

Differential pressure from the district heating  $\Delta p_o = \Delta p_a + \Delta p_v$ 

Rewritten the flow can be expressed as

$$= \sqrt{\frac{\Delta p_o}{1/(k_{va})^2 + 1/(k_{vv})^2}}$$

The max. flow is limited by the min. differential pressure of the district heating  $\Delta p_{^{0}\text{min}}$  , the max. capacity of the system  $k_{\text{va}_{\text{max}}}$ , and of the max. capacity of the controller k<sub>vvs</sub>.

Max. system flow: 
$$Q_{max} = \sqrt{\frac{\Delta p_{o_{min}}}{1/(k_{va_{max}})^2 + 1/(k_{vvs})^2}}$$

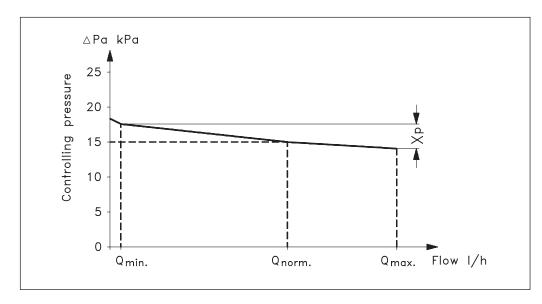
#### Settings

AVPL can be set to any differential pressure within the range 5 kPa to 25 kPa (0.05 bar to 0.25 bar). The factory pre-setting of the AVPL is 10 kPa (0.1 bar), 1 kPa for each turn.

As mentioned above, the proportional effect depends on the correlation between the controller valve's degree of opening and the deviation between the controlled and set differential pressure. Furthermore, the deviation depends on the actual differential pressure across the control valve and the actual control setting.

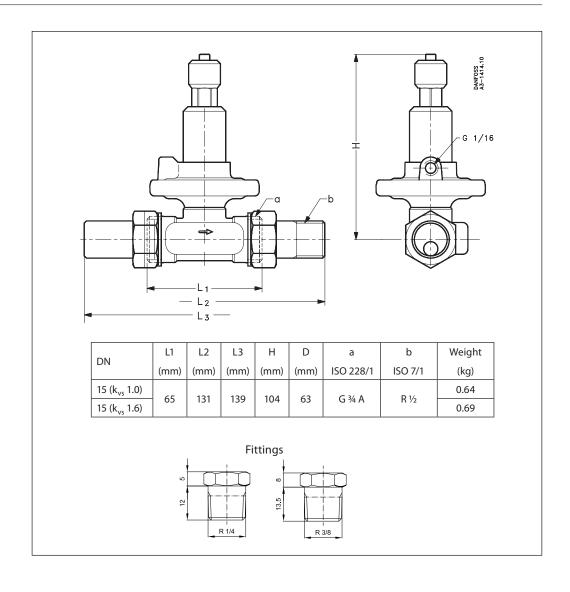
The chosen deviation is large enough to ensure a stable control and small enough to keep the controlled differential pressure within acceptable limits.

The controller is designed in such a way that the controlled and the set differential pressures are equal when the flow is about 250 l/h for AVPL 1.0 and 400 l/h for AVPL 1.6 at nominal differential pressure 50 kPa ( $\Delta p_v$ ). At min. and max. flow the controlled differential pressure deviates from the set pressure with ±1...3 kPa, depending on the actual differential pressure and setting.



## Differential pressure controller AVPL (PN 16)

## **Dimensions**



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